

Gas and Liquid Phase Sensitivity of “Love” Waves

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Overview

1. Layer-Guided Acoustic Waves

- Love waves v SH-APMs
- Dispersion curves and phase speed mass sensitivity
- Dispersion and group velocity
- Polymer waveguides and the “Sauerbrey” equation

2. Experimental Data

- Existence of layer-guided SH-APMs
- Group velocity mass and liquid sensitivity

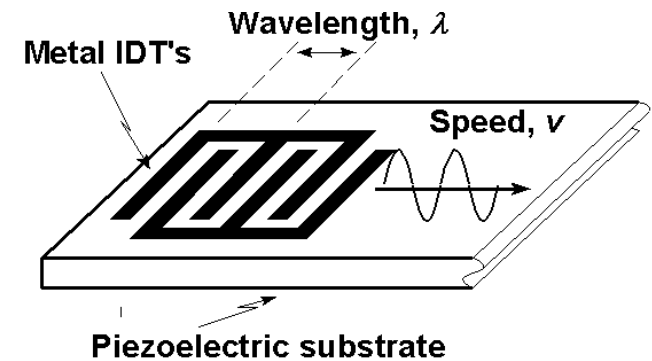
3. Love Waves and Frequency

- Higher frequency and multiple modes
- Frequency hopping

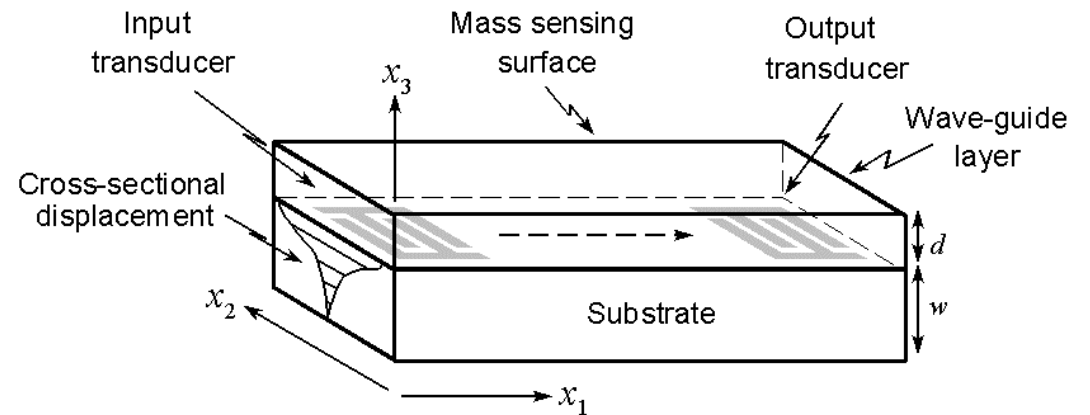
4. Summary

Love Waves v SH-APMs

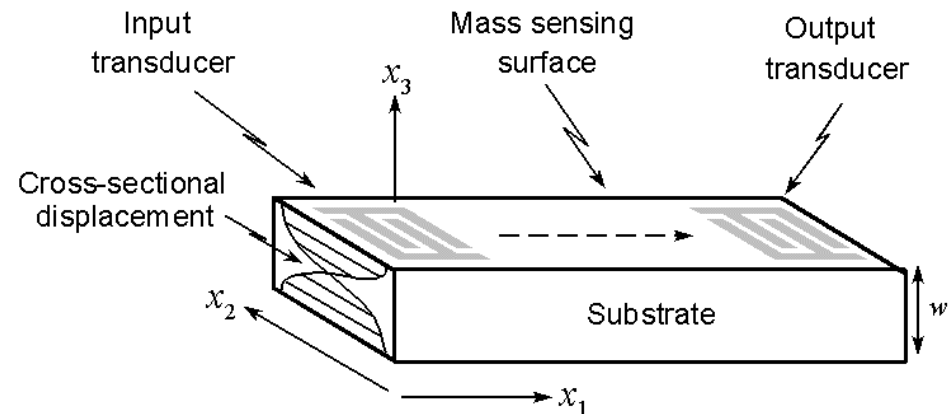
- Surface Acoustic Wave (SAW)



- Love Wave
Layer guided SH-SAW
with $v_l < v_s$



- SH-APM
Substrate resonance

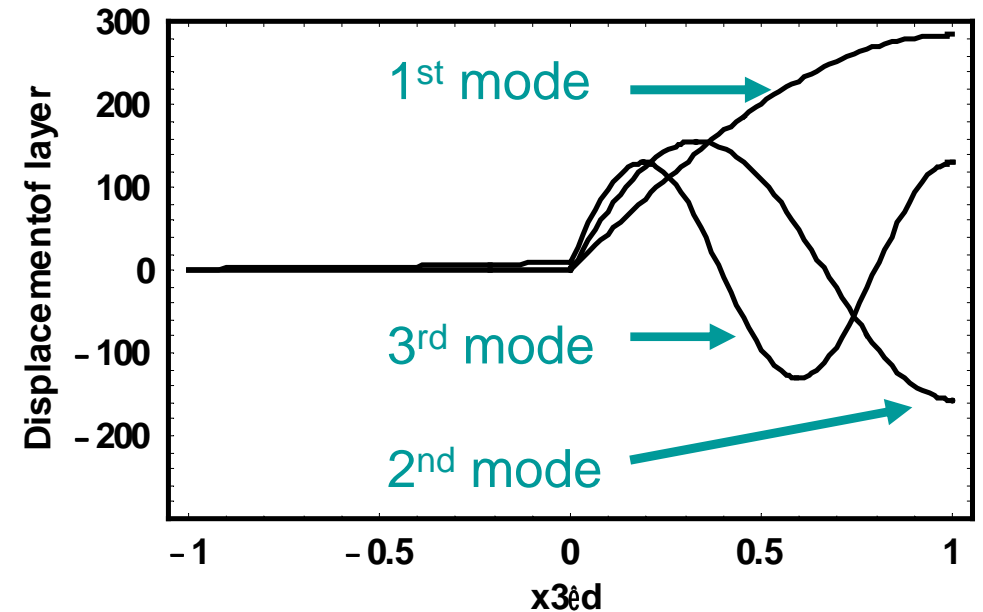
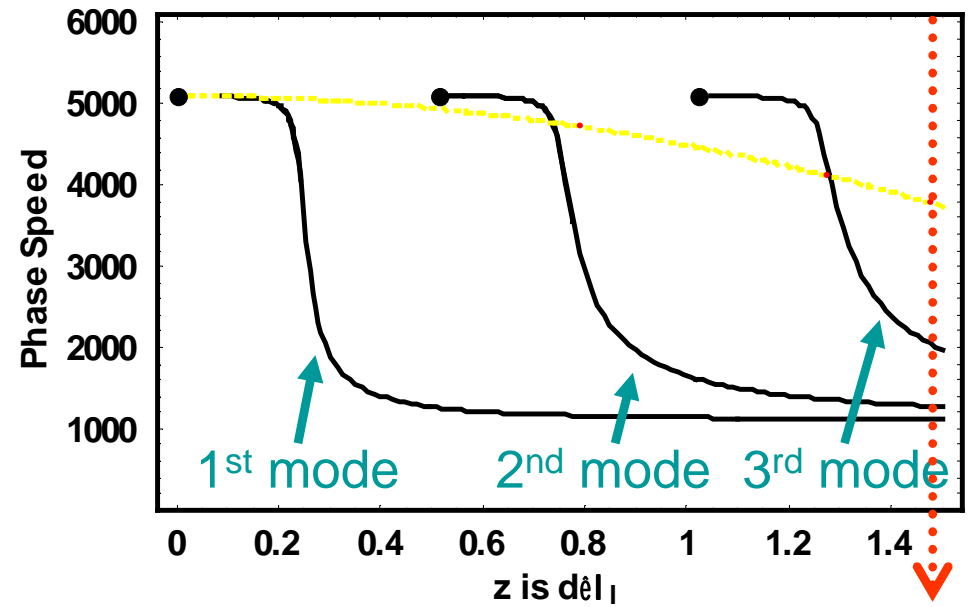


Love Waves

- Theoretical dispersion curve

(Insertion loss is unchanged by an elastic guiding layer)

- Displacements for first three modes ($z=1.3$)



Layer-Guided SH-APMs

- Generalized Dispersion Equation¹

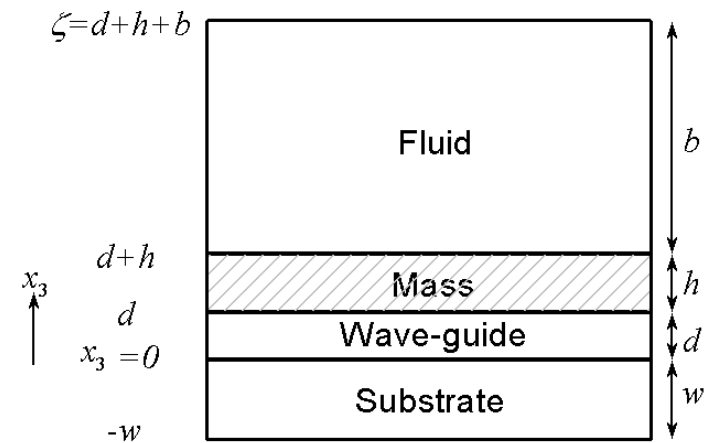
Layer and substrate displacements

$$\underline{u}_l = (0,1,0) \left[A e^{-jT_l x_3} + B e^{jT_l x_3} \right] e^{j(\omega t - k_1 x_1)}$$

$$\underline{u}_s = (0,1,0) \left[C e^{T_s x_3} + D e^{-T_s x_3} \right] e^{j(\omega t - k_1 x_1)}$$

Eqns of motion $\Rightarrow T_l$'s and T_s

Boundary conditions \Rightarrow dispersion eqn



- Substrate + Layer Solutions

T_s real $\Rightarrow v < v_s \Rightarrow$ "Love" Waves

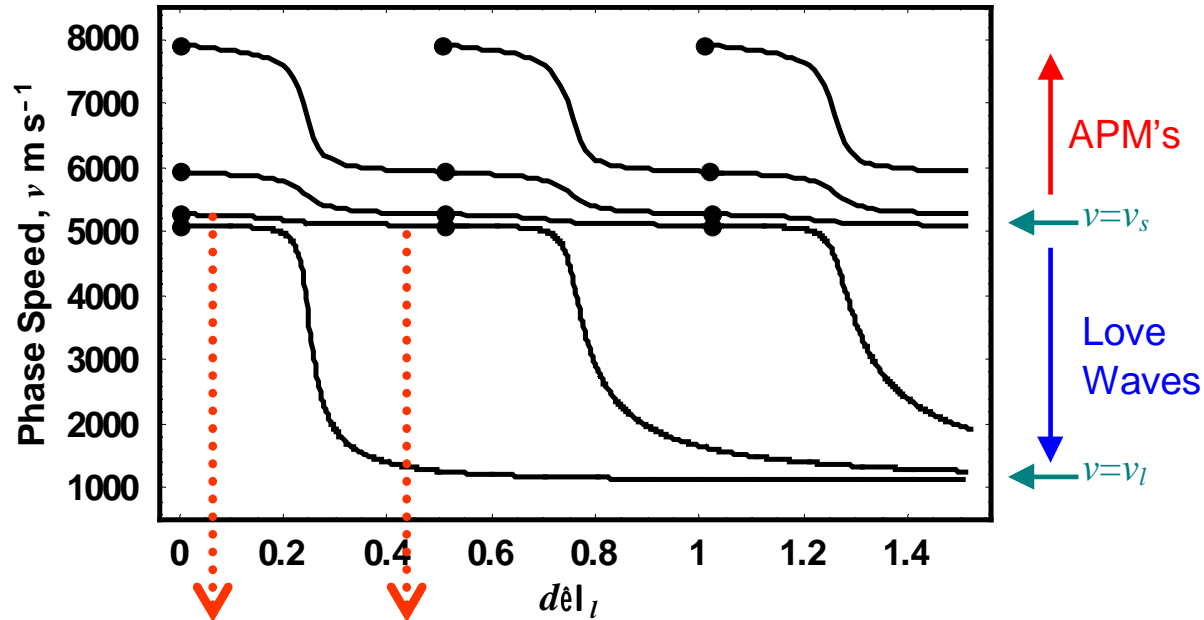
$T_s = jk_s$ with k_s real $\Rightarrow v > v_s \Rightarrow$ "Layer guided SH-APMs"

¹McHale et al, Europhys. Lett. (2002) 58, 818-822, J. Appl. Phys. (2002) 91, 5735-5744.

McHale et al, "Mass, liquid and polymer sensitivity", Accepted J. Appl. Phys. (2002).

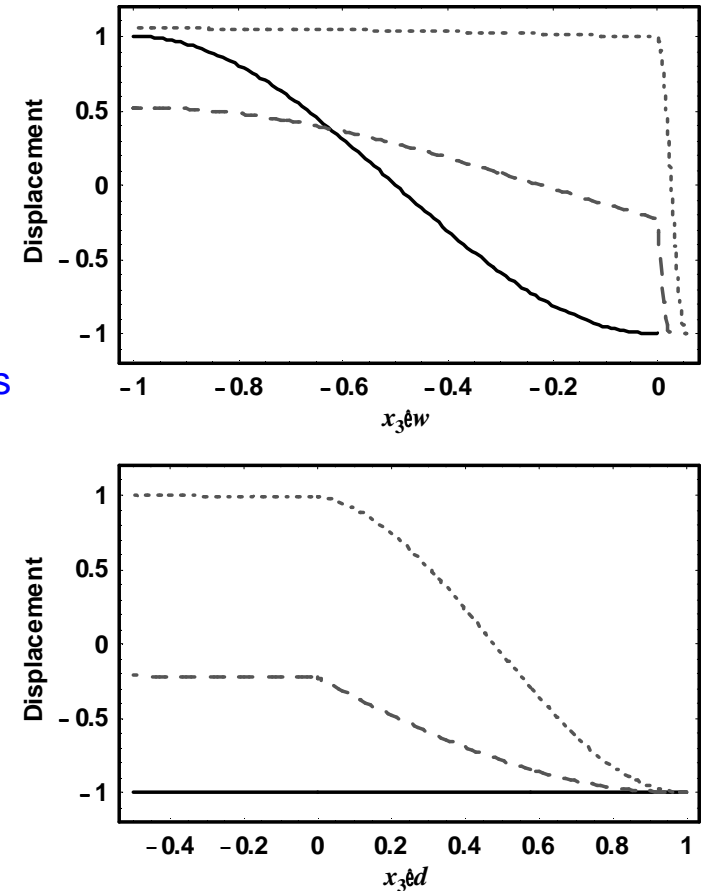
Substrate + Mass Guiding Layer

Dispersion Curve



Points = Anti-node moving from substrate to layer

Evolution of 1st SH-APM



Solid \rightarrow dashed
with increasing guiding

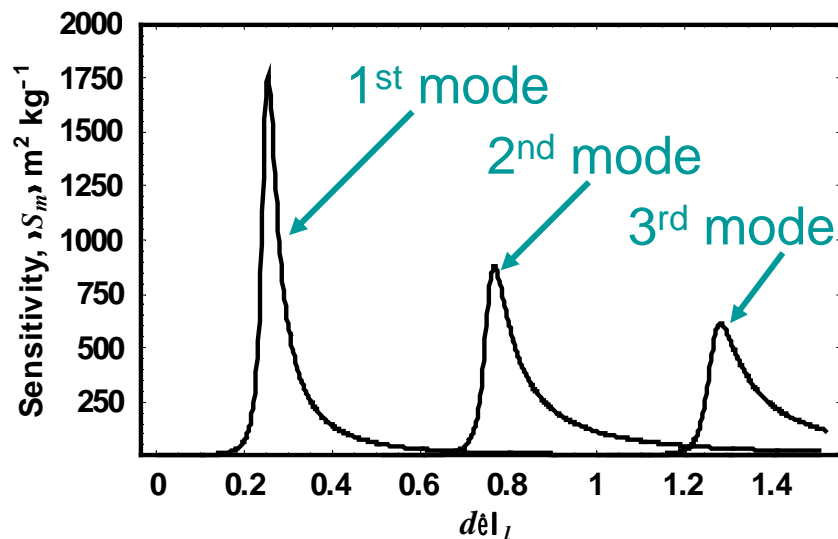
Phase Speed Mass Sensitivity

$$S_m = \lim_{\Delta m \rightarrow 0} \frac{1}{\Delta m} \left(\frac{\Delta v}{v_o} \right) \approx \frac{f_o}{\rho_l |v_l|} \left(\frac{d \log_e v}{dz} \right)_{z_0}$$

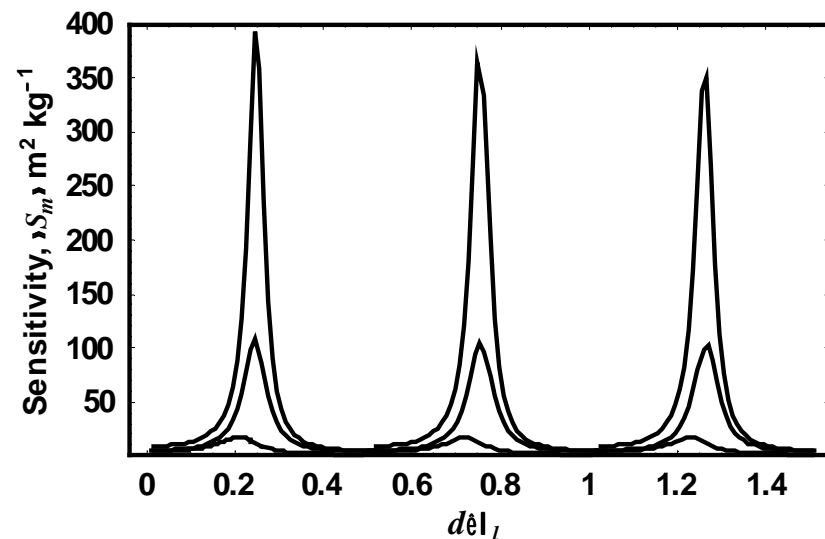
Δm is mass per unit area being sensed, $z = df/v_l$ is the normalized thickness

"Rigid" mass \Rightarrow Mass sensitivity is slope of dispersion curve¹

Love Waves



Layer-Guided SH-APMs



¹McHale *et al*, J. Appl. Phys. (2002) 91, 9701-9710.

Dispersion and Group Velocity

- Guiding Layer Induces Dispersion^{1,2}

Phase velocity

$$v = f\lambda \quad \text{or} \quad v = \omega/k$$

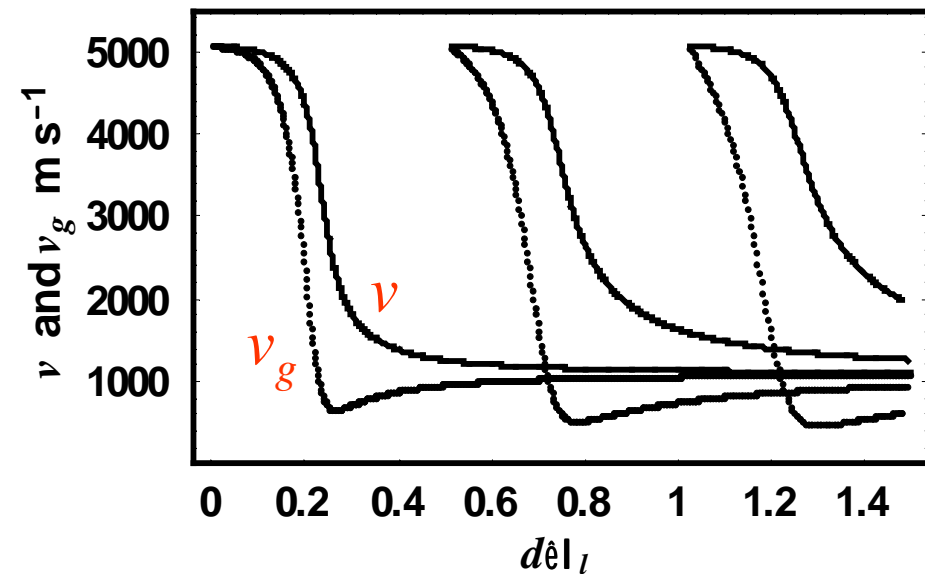
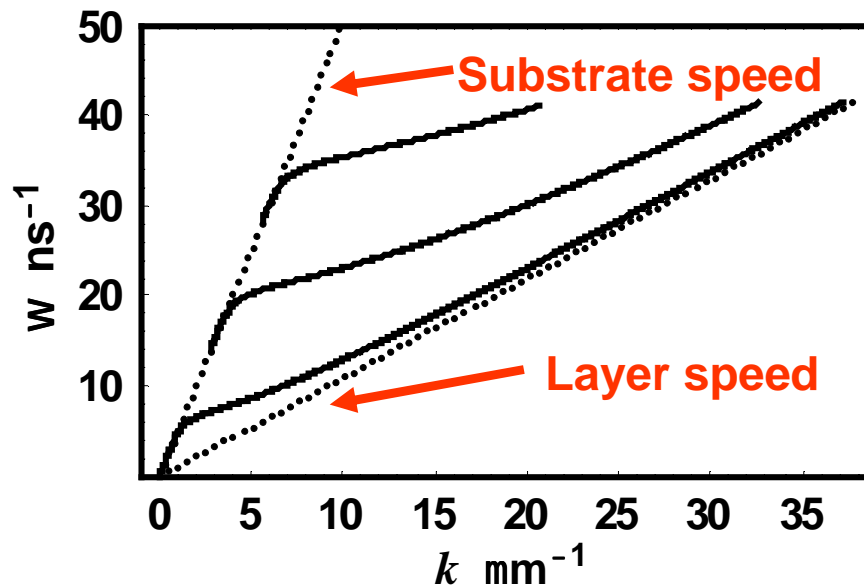
Group velocity

$$v_g = d\omega/dk$$

Group velocity is slope of the (ω, k) dispersion curve

Example

0.25 μm polymer guiding layer on Quartz with $w \rightarrow \infty$



¹McHale et al, "Sensitivity from group and phase", J. Appl.Phys. (2002) vol 92

²Martin et al, "Experimental study of Love wave", IEEE Sensor Journal (2002)

Group Velocity Mass Sensitivity

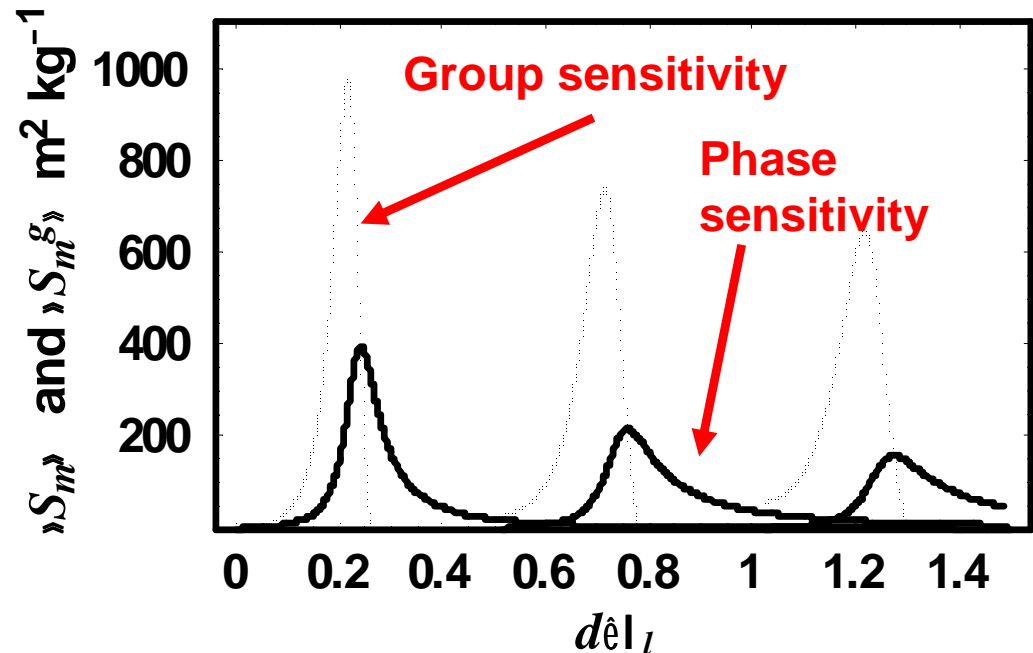
"Rigid" mass

Mass sensitivity is fractional deviation of the phase velocity from the group velocity divided by mass per unit area due to the guiding layer

$$S_m \approx \frac{1}{\rho_l d} \left(1 - \frac{v}{v_g} \right) = \frac{1}{\rho_l d} \frac{(v_g - v)}{v_g}$$

- Define a Group Velocity Sensitivity

$$S_m^g = \frac{f_0}{\rho_l v_l} \left(\frac{d \log_e v_g}{dz} \right)_{z=z_0}$$



Polymer Waveguide with Polymer Loading

Generalized Sauerbrey Equation

Complex velocity shift

$$\frac{\Delta v}{v_o} \approx \left(\frac{1 - v_f^2/v_o^2}{1 - v_l^2/v_o^2} \right) \left(\frac{d \log_e v}{dz} \right)_{z=z_0} \left(\frac{\tan(T_f^o h)}{T_f^o h} \right) \frac{\omega \rho_f h}{2\pi v_l^\infty \rho_l}$$

Complex slope factor
from polymer waveguide

Care Needed

1. Dispersion
2. Slope depends on ω

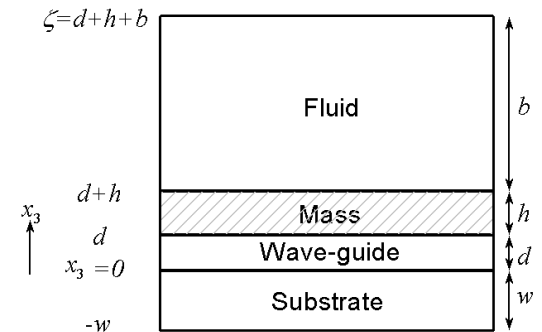
tanx/x factor gives mass/liquid loading limits

$$\left(\frac{\tan(T_f^o h)}{T_f^o h} \right) \rightarrow \begin{cases} 1 & h \rightarrow 0 & \text{solid limit} \\ \frac{-\sqrt{-2j}}{2h(1 - v_f^2/v_o^2)} \sqrt{\frac{2\eta_f}{\omega \rho_f}} & h \rightarrow \infty \text{ and } \omega\tau \rightarrow 0 & \text{liquid limit} \end{cases}$$

Insertion Loss for Polymer Waveguide

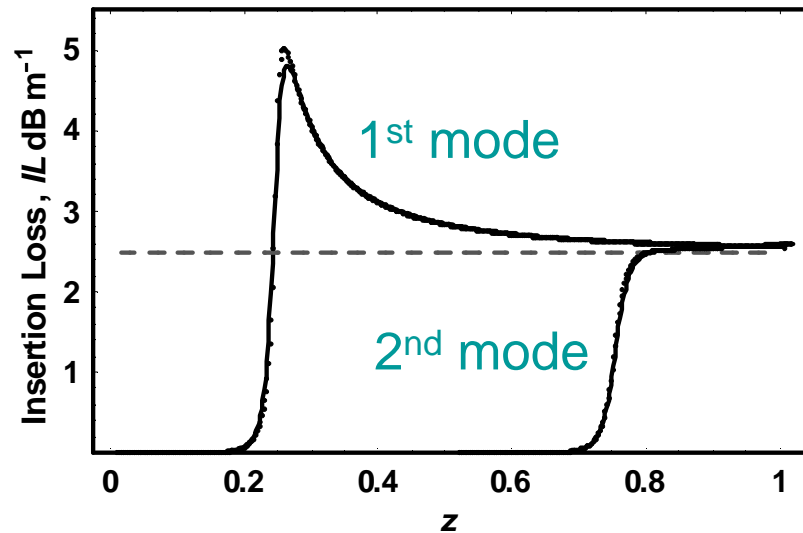
Cases considered

1. Wave-guide layer is viscoelastic
2. Mass layer deposited from liquid or from vacuum
3. Mass may be omitted (i.e. liquid phase sensitivity)

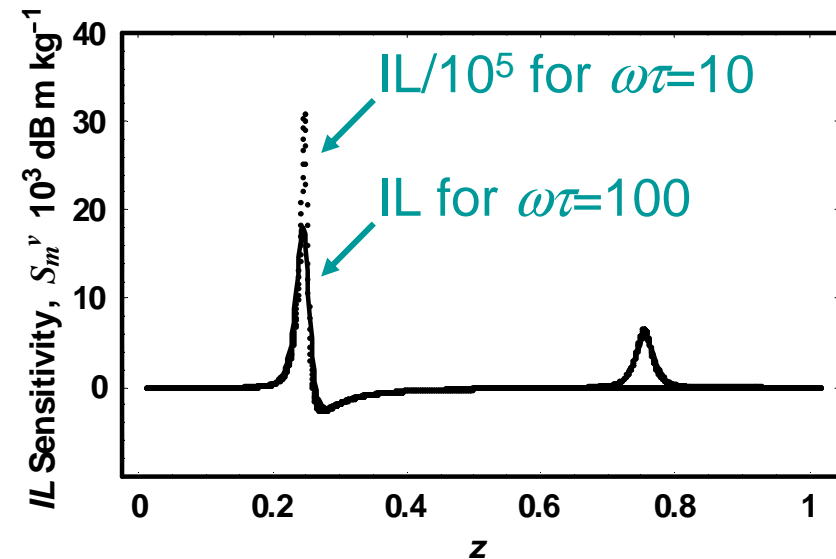


Mass/liquid sensitivity can be derived for phase velocity & insertion loss

Love Wave Insertion Loss



Love Wave IL Sensitivity



¹McHale et al, "Mass, liquid and polymer sensitivity", Accepted J. Appl. Phys. (2002).

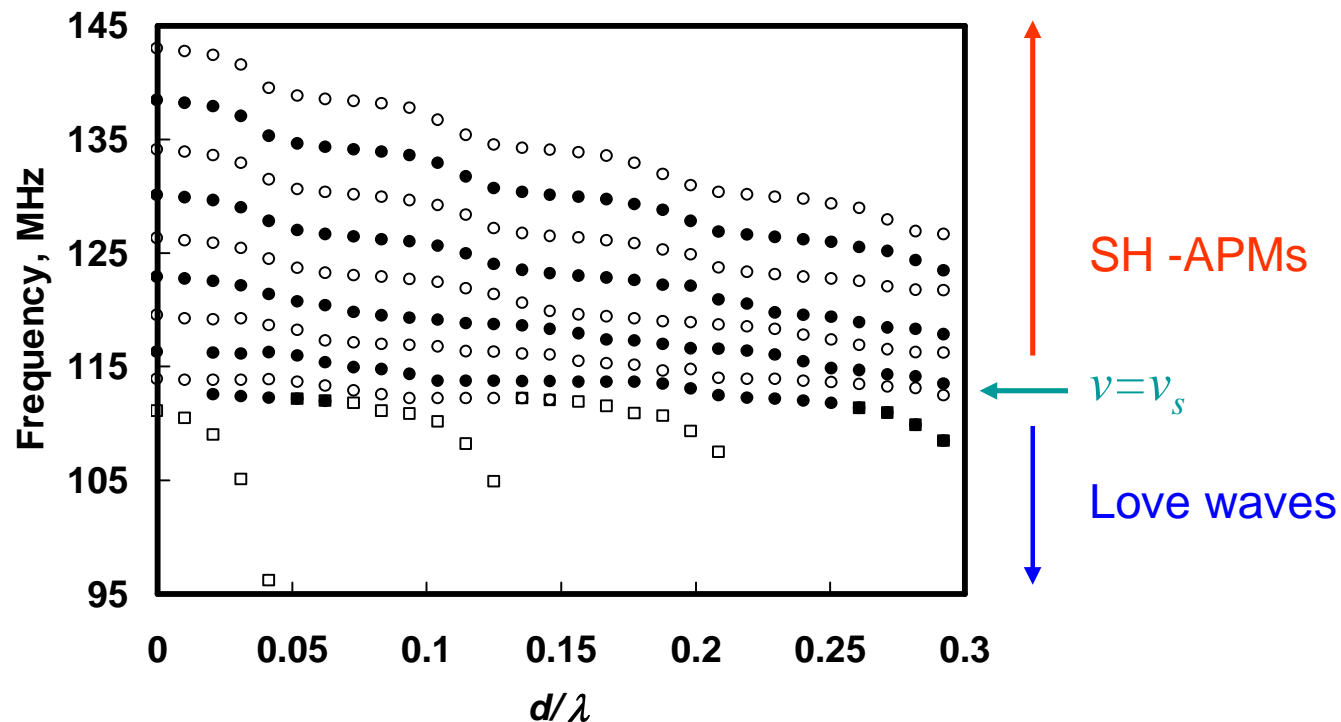
Data for Layer-Guided SH-APM

- **Layer-Guided SH-APM Modes**

Prop. Orthog. to x -axis of thinned ($200\ \mu\text{m}$) ST-Q substrate
110 MHz surface skimming bulk wave (SSBW)

SSBW \rightarrow Love wave by a spin-coated photoresist layer

Old mask so insertion loss high (axis is d/λ with λ =IDT period)



Experimental Data for SH-APM

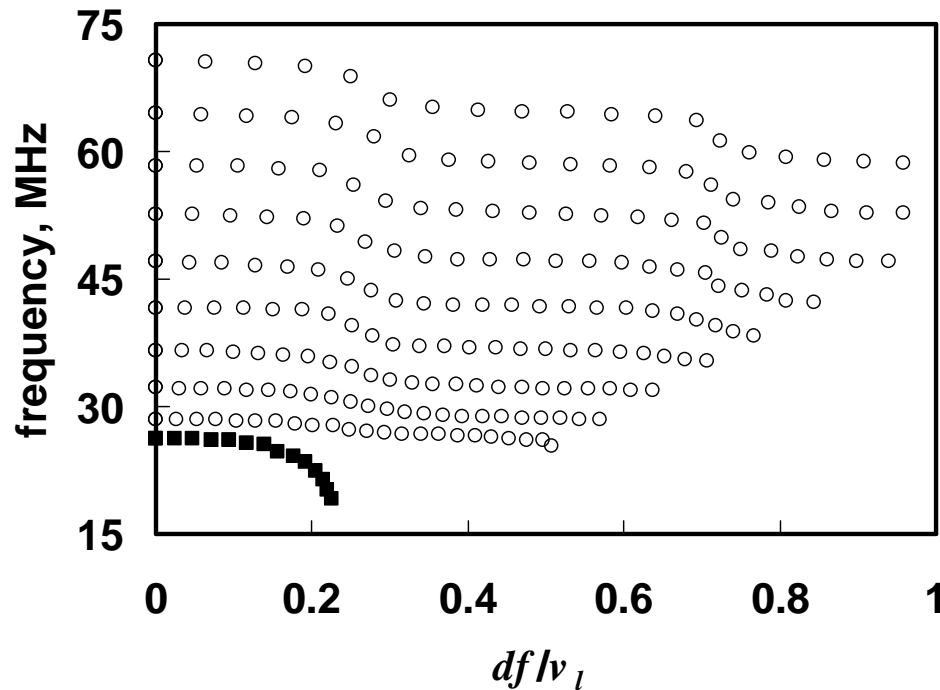
- **Layer-Guided SH-APM Modes¹**

Prop. Orthog. to x -axis of thinned ($200\ \mu\text{m}$) ST-Q substrate

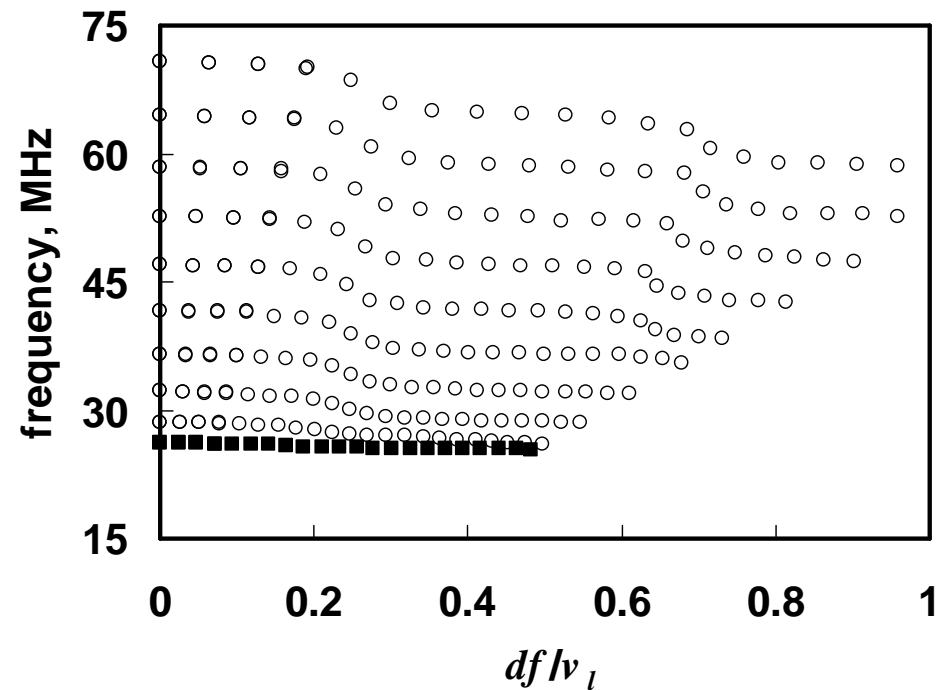
25 MHz surface skimming bulk wave (SSBW)

Plate modes clearly resolved

Coatings on Same Face as IDTs



Coatings on Opposing Face to IDTs



¹F. Martin, PhD Thesis, Nottingham Trent University (2002)

Group Velocity Data - Solids

- Phase and Group Velocity

36° XY LiTaO₃

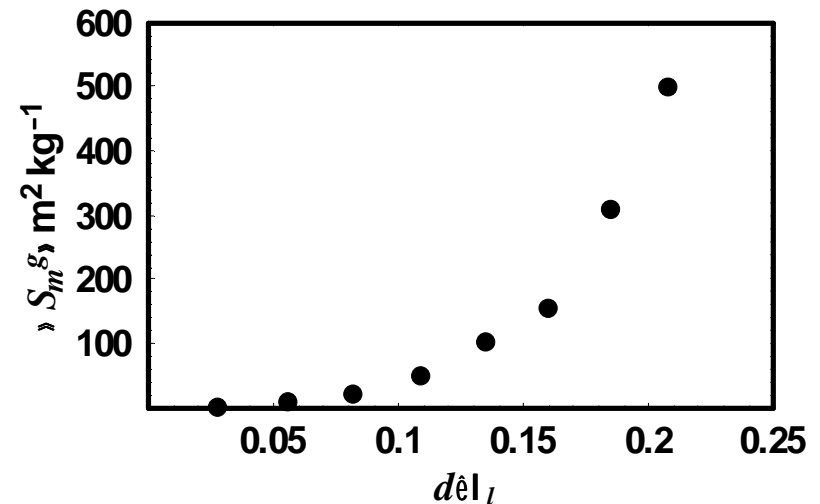
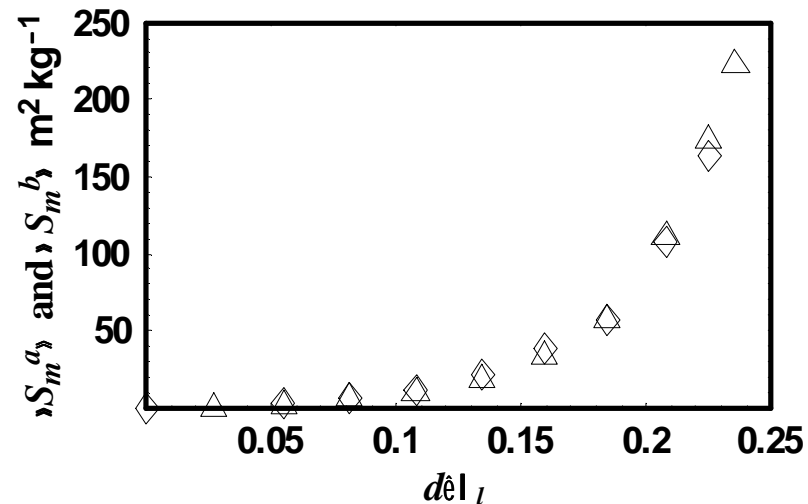
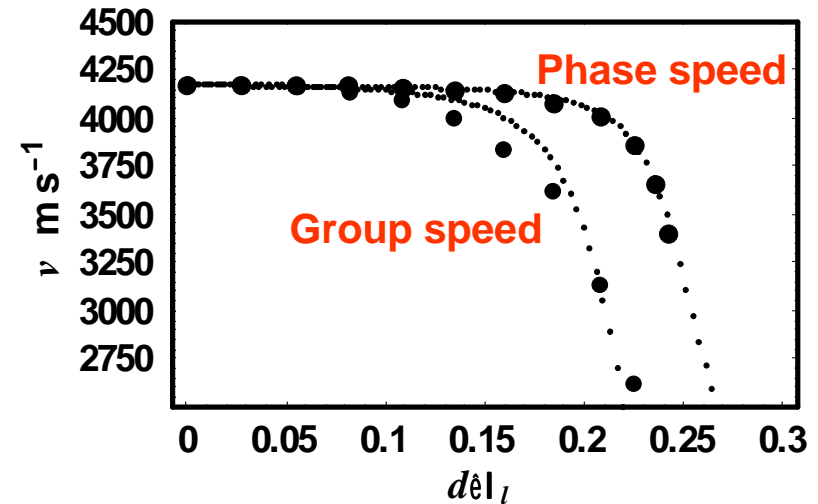
Hardbaked photoresist

Dotted curves are fits

- Mass Sensitivity

$$S_m^b = \frac{1}{\rho_l d} \left(1 - \frac{v}{v_g} \right) \quad S_m^a = \frac{1}{\rho_l} \left(\frac{d \log_e v}{dx} \right)_{x=d}$$

$$S_m^g = \frac{1}{\rho_l} \left(\frac{d \log_e v_g}{dx} \right)_{x=d}$$



Group Velocity Data - Liquids

- Deposition of Guiding Layer

ST-Quartz + photoresist

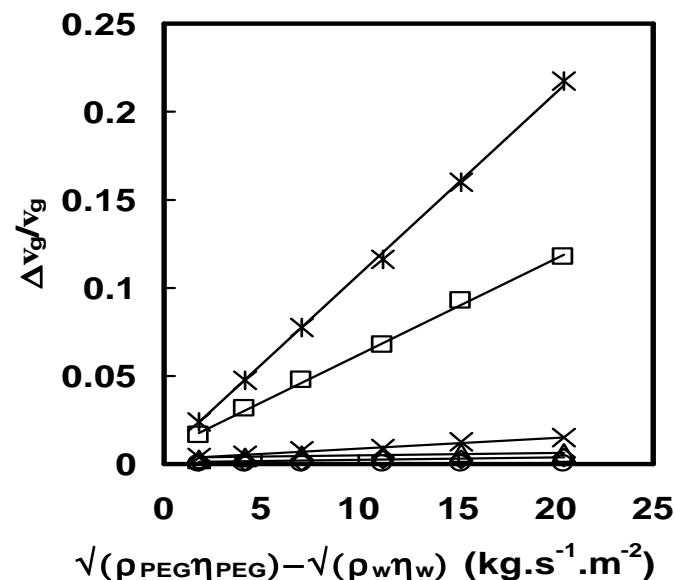
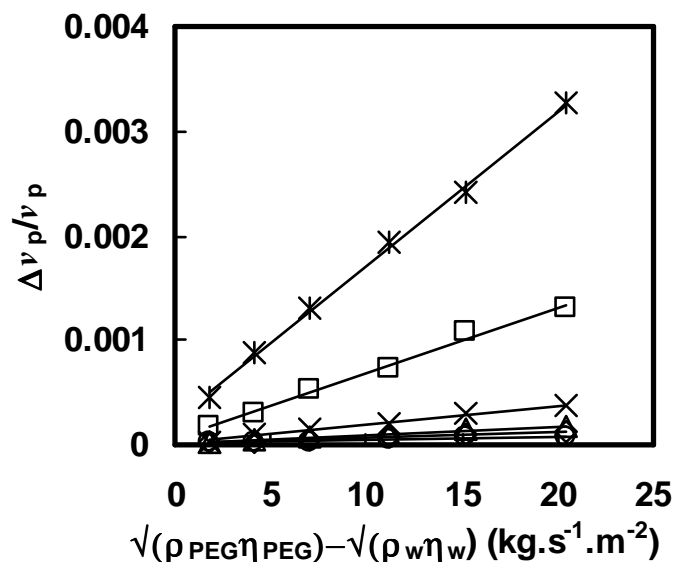
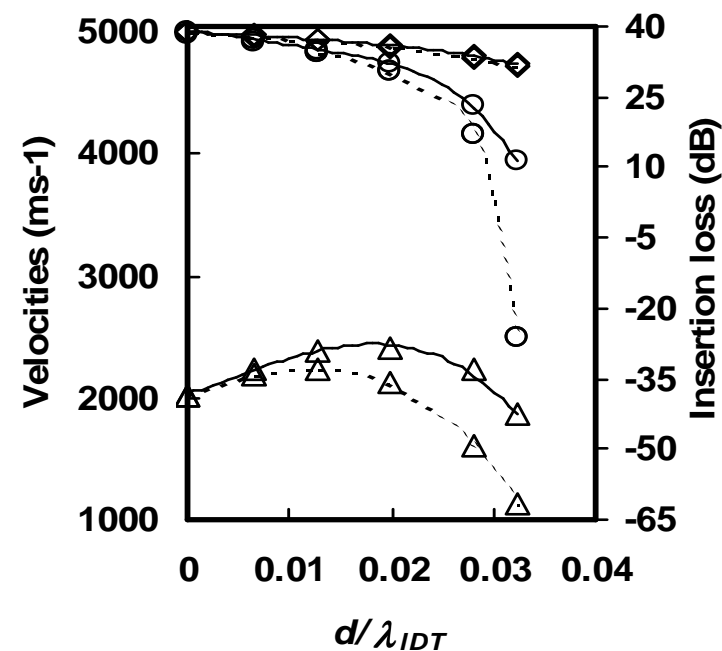
Poly (ethylene glycol) solutions

◆ = Phase velocity ○ = Grp Velocity

△ = Insertion loss Dotted = water

- Sensitivity at Operating Points

Phase and group velocities



Love Waves and Higher Frequency

- Established QCM Sensor Principle

Mass sensitivity \propto Fundamental frequency
Higher frequency \Rightarrow Higher mass sensitivity

- Love Waves on a (Semi-) Infinite Substrate

Controlling dimensionless variable is $z = d/\lambda_l = df/v_l$

$$S_m = \lim_{\Delta m \rightarrow 0} \frac{1}{\Delta m} \left(\frac{\Delta \nu}{\nu_o} \right) \approx \frac{f_o}{\rho_l v_l} \left(\frac{d \log_e \nu}{dz} \right)_{z_0}$$

Mass Sensitivity \propto Frequency \times Function of z_0
Normalized thickness at operating point $z_0 \propto d \times f$

Higher Frequency Operation^{1,2}

Routes

1. Increase fundamental frequency
2. Hop the frequency to a harmonic

Issues

1. Change of Love wave mode?
2. Const. guiding layer thickness?

- Frequency Increase at Constant z_0

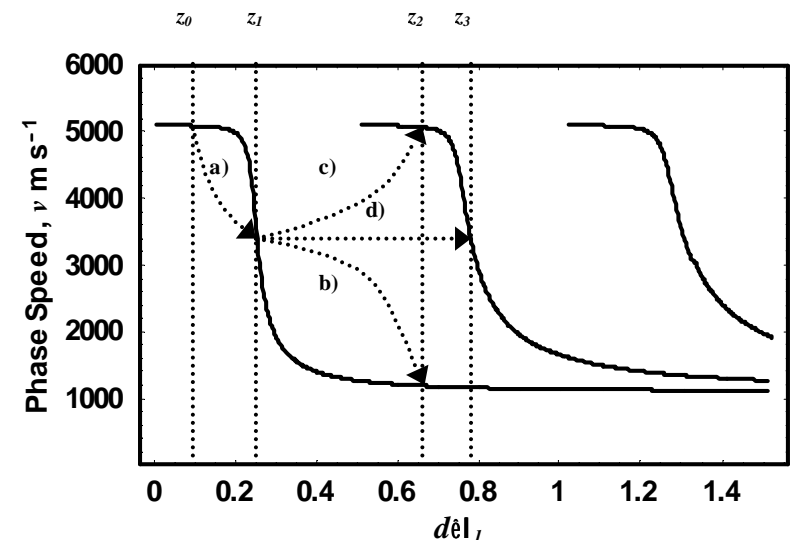
Reduce d as $1/f$ \Rightarrow No change on dispersion curve
 \Rightarrow Mass sensitivity scales with f

- Frequency Hopping at Constant d

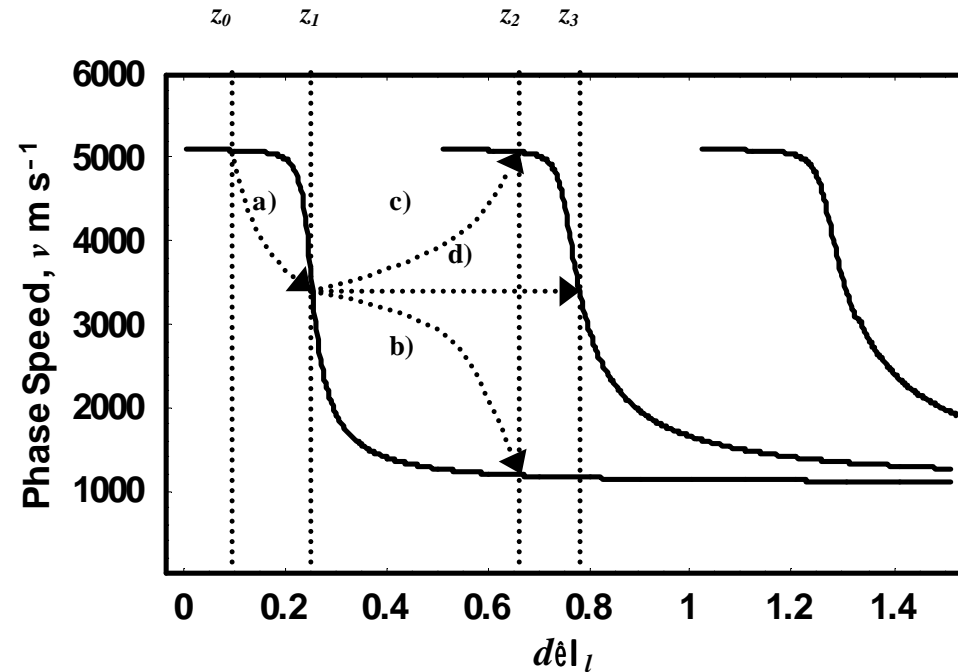
Four example transitions

Same mode \Rightarrow lower/higher sensitivity

Change mode \Rightarrow lower/higher sensitivity



Frequency Hopping Transitions



No Mode Change

- Transition a) ⇒ Higher mass sensitivity
- Transition b) ⇒ Lower mass sensitivity

Mode Change

- Transition c) ⇒ Lower mass sensitivity
- Transition d) ⇒ Higher mass sensitivity

Maximum Increase in Mass Sensitivity

Ratio of frequencies × ratio of max slopes of modes

i.e. scales by less than by the frequency ratio

Summary

Achievements

- **Unifying theory**
Love wave and SH-APM's
- **New sensor**
Layer-guided SH-APM's
- **Mass/liquid sensitivity predictions**
Phase velocity and insertion loss
Relation to group velocity
- **Love wave frequency response**
Mode and non-mode changes

Lessons

- **Higher order Love waves**
from SH-APM's
- **Guiding layer on SH-APM's**
significant increase in sensitivity
- **Higher frequency**
Higher or lower sensitivity
Frequency scaling of mode peak
- **Love waves \Rightarrow strong dispersion**
Group and phase velocity differ

The End
